



3ème Atelier des contributeurs
Paris 30-31 Mai

Classification supervisée et détection de changements à partir d'images d'*Haïti* à haute résolution (*CSK/GeoEye* ou *CSK/Pleiades*) par utilisation de méthodes Markoviennes.

Supervised classification and change detection from high resolution (*CSK / GeoEye* or *CSK / Pleiades*) images from *Haïti* using Markovian methods.

Presented by

Josiane Zerubia¹

In collaboration with

A. Voisin¹, V. Krylov¹, I. Hedhli¹⁻², G. Moser² and S. B. Serpico²

Objectives

- Supervised image classification
- Change detection (using 2 dates or temporal series)
- General and sufficiently robust to different types of images.

Key points

- Focus on (single-pol) radar (SAR) imagery
- extension to multi-sensor data (CSK/ GeoEye or CSK/Pleiades).

General applications

- Global detection of urban areas, that are critical w.r.t. populations (risk management).
- Infrastructures mapping.
- ...

Optical imagery



Port au Prince (GeoEye) © GeoEye

- Here considered as an **additional information to SAR.** (0.5 m)

SAR imagery



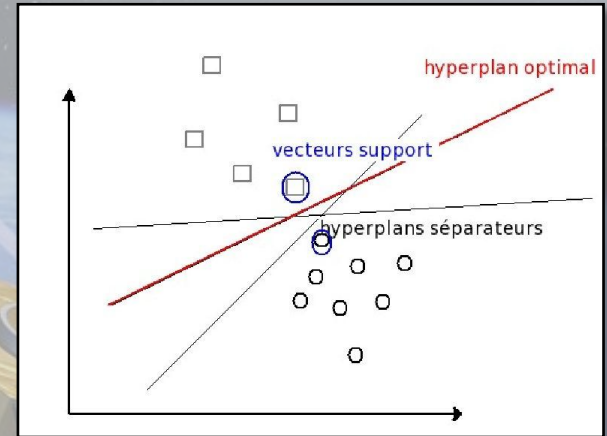
Port au Prince (CSK) © ASI

- All-weather conditions.
- SAR amplitude.
- SpotLight (1m), **StripMap (2.5m)**, PingPong (10m).
- Challenge: Speckle noise.

Supervised classifiers

Support Vector Machine (SVM)^[1]

- Well-chosen projections to reformulate the classification problem as a resolution of quadratic optimization problem, maximizing the distance between the separating border and the closest learning samples.
- Extension to nonlinear classification through kernel functions.



K-nearest neighbors (K-NN)

- Used to model the probability density functions.
- Integrated in a MRF model.
- Supervised estimation of the probability of a given pixel by using a majority vote on the *K-nearest (distance rule) known pixels*.
- *K estimated by cross validation.*

[1] V. Vapnik, [The Nature of Statistical Learning Theory], Springer, 2nd edition, (2000).

Proposed methods

2 supervised contextual classifiers based on MRF :

- MRF with **textural features**
- Hierarchical MRF integrating a **prior update**

Contributions of A.Voisin (PhD), V. Krylov (Post-Doc)

2 supervised contextual classifiers :

- Shared learning: statistical modeling of the input images, by using **adapted finite mixtures** and ***d*-variate copulas**.
- Integration of the statistics in Markovian models: MRF with **textural features**, and hierarchical MRF integrating a **prior update**

[2] A. Voisin, G. Moser, V. Krylov, S. B. Serpico, and J. Zerubia, "Classification of very high resolution SAR images of urban areas by dictionary-based mixture models, copulas and Markov random fields using textural features," in [Proc. of SPIE Symposium on Remote Sensing], 783000 (2010).

[3] A. Voisin, V. Krylov, G. Moser, S. B. Serpico, and J. Zerubia, "Multichannel hierarchical image classification using multivariate copulas", in [Proc. of IS&T/SPIE Electronic Imaging], 82960K (2012).

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Joint PDF

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Single-scale Markovian model

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Hierarchical Markovian model

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Experimental results

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Conclusion and Perspectives

1

Joint PDF

❖ Marginal PDF modeling

❖ Joint PDF modeling

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Single-scale Markovian model

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Conclusion and Perspectives

Copulas : Overview

X The reflectivity in SAR and optical bands are very different from each other

How to address the complicated problem of SAR + optical PDF modeling ?

- 1 First, estimate the marginal class-conditional statistics of each SAR/optical channel separately via distinct finite mixtures.
- 2 then, model the joint PDF through **copulas**.^[4]

A copula is a kind of distribution function. Copulas are used to describe the **dependence** between **random variables**.

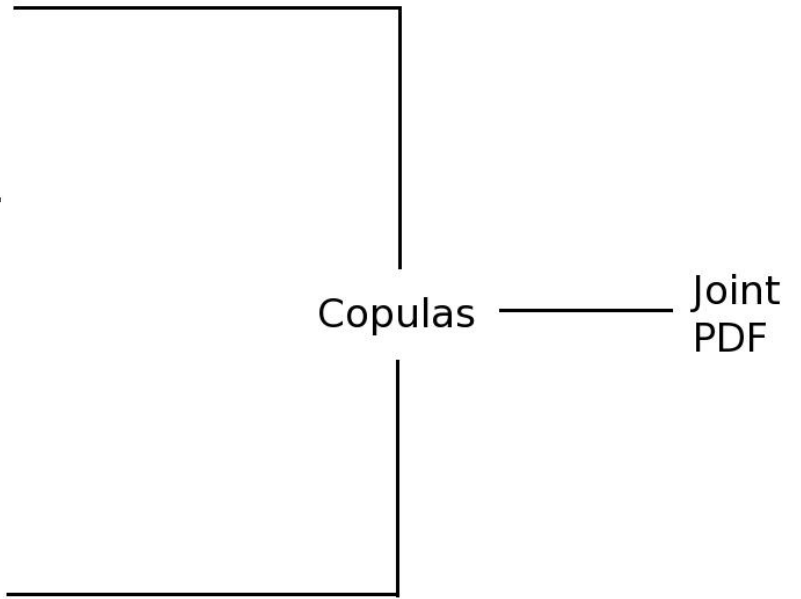
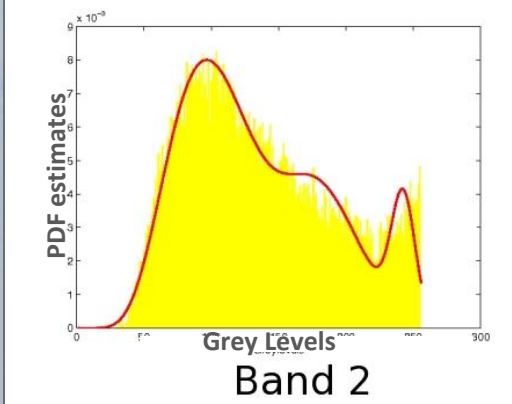
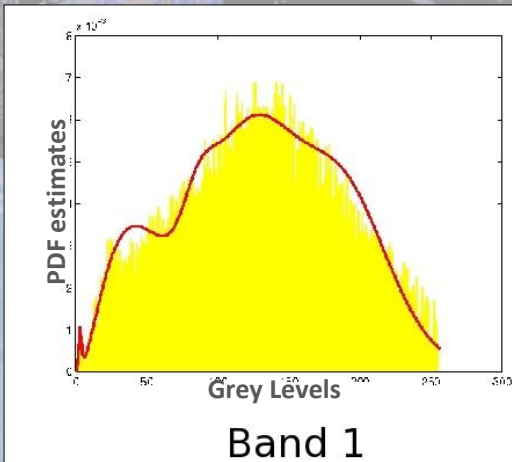
Copula	$C(u_1, \dots, u_d)$	$\theta(\tau)$	τ interval
Clayton	$\left[\left(\sum_{i=1}^d u_i^{-\theta} \right) - d + 1 \right]^{-1/\theta}$	$\theta = \frac{2\tau}{1-\tau}$	$\tau \in]0; 1]$
AMH (Ali-Mikhail-Haq)	$\frac{\prod_{i=1}^d u_i}{1 - \theta \prod_{i=1}^d (1 - u_i)}$	$\tau = \frac{3\theta - 2}{3\theta}$	$\tau \in$ $\left[-0, 182; \frac{1}{3} \right]$
Gumbel	$\exp \left(- \left[\sum_{i=1}^d (-\ln u_i)^\theta \right]^{1/\theta} \right)$	$\theta = \frac{1}{1-\tau}$	$\tau \in [0; 1]$

In order to maximize flexibility in the proposed method, a **dictionary approach** is adopted for copula modeling

[4] Nelsen, R. B., [An introduction to copulas], Springer, New York, 2nd ed. (2006).

Joint PDF : Overview

For each class m , and at each resolution (multi-resolution case): Build a joint PDF.



Note : the two bands may come from multiple polarizations (e.g., CSK pingpong) and/or multiple sensors (e.g., CSK stripmap and GeoEye).

Marginal PDF modeling

For each input image, we want to estimate the distributions of each class $m \in [1; M]$. The PDF $f_m^{(j)}(y^{(j)})$ of the j^{th} input band, $j \in [1; d]$, is modeled via **finite mixtures**:

$$f_m^{(j)}(y^{(j)}) = p_m^{(j)}(y^{(j)} | \omega_m) = \sum_{i=1}^{K^{(j)}} P_{mi}^{(j)} p_{mi}^{(j)}(y^{(j)} | \theta_{mi}^{(j)})$$

$y^{(j)}$ is a greylevel

$P_{mi}^{(j)}$ are the mixing proportions such that $\sum_{i=1}^K P_{mi}^{(j)} = 1$

$\theta_{mi}^{(j)}$ is the set of parameters of the i^{th} PDF mixture component of the m^{th} class

m_i is the i -th component of the mixture that models the class m

Advantages of finite mixtures

- ❖ Unimodal density does not accurately model SAR amplitude statistics given their heterogeneity.
- ❖ Each component (of the sum) may reflect the contribution of the different materials.

Marginal PDF modeling: Optical image case

Gaussian distribution is a usually accepted model for optical imagery:

$$p_{mi}(y|\theta_{mi}) = \frac{1}{\sqrt{2\pi\sigma_{mi}^2}} \exp\left[-\frac{(y - \mu_{mi})^2}{2\sigma_{mi}^2}\right], \quad \text{with } \theta_{mi} = \{\mu_{mi}, \sigma_{mi}^2\}.$$

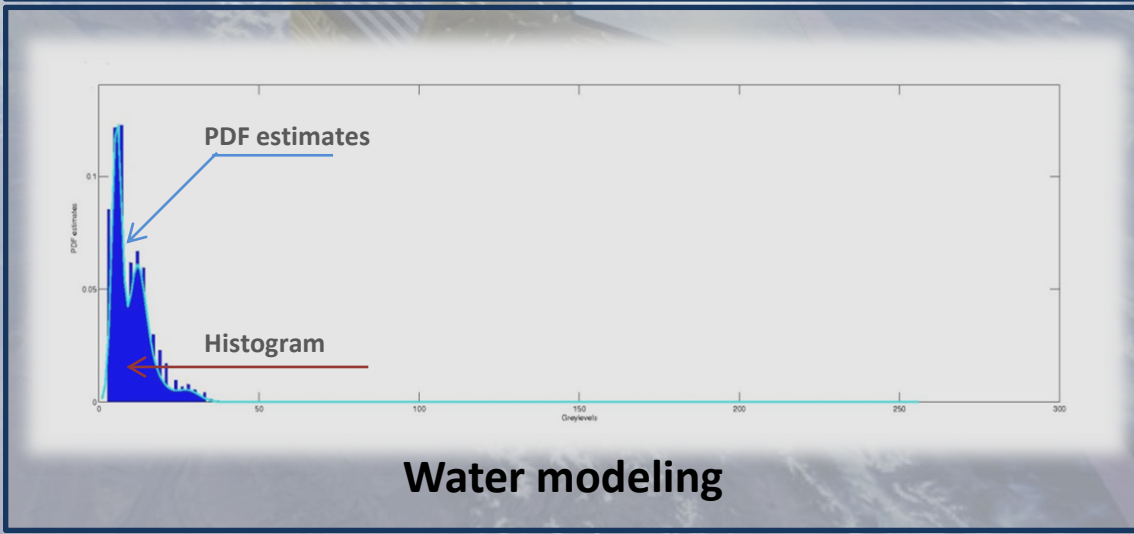
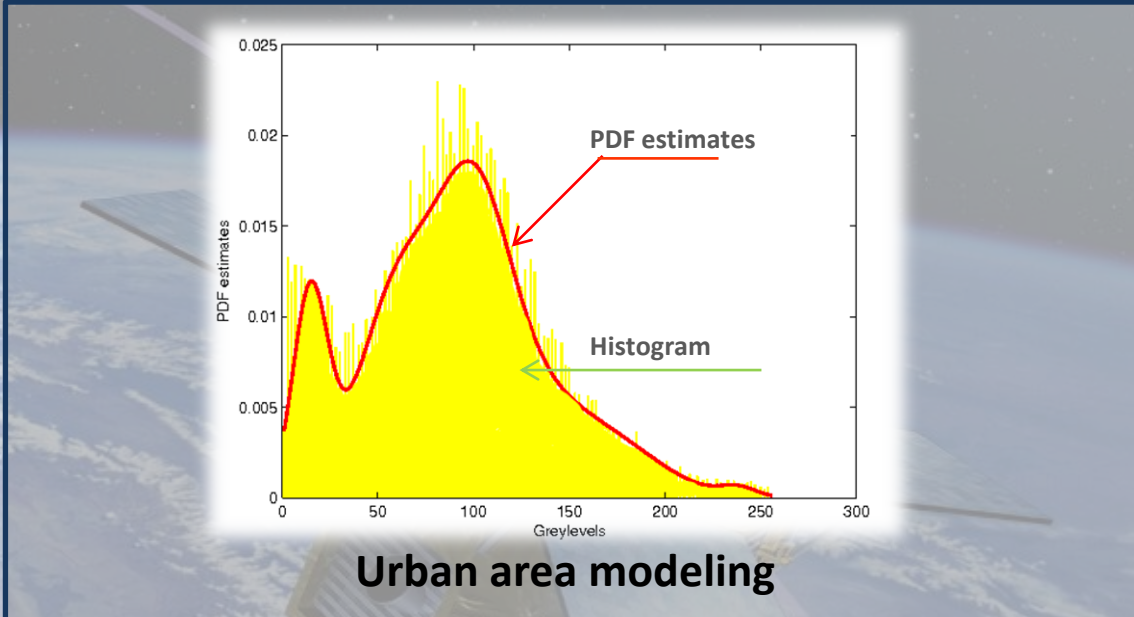
The parameters p_{mi} , θ_{mi} are estimated within a SEM* algorithm .

* Stochastic Expectation Maximization algorithm [5]

Experimental validation



Port au Prince (©GeoEye)
(0.5 m)



Marginal PDF modeling: SAR image case^[6]

P_{mi} , θ_{mi} and K are estimated within a SEM algorithm combined with the method of log-cumulants. Best family chosen through ML.

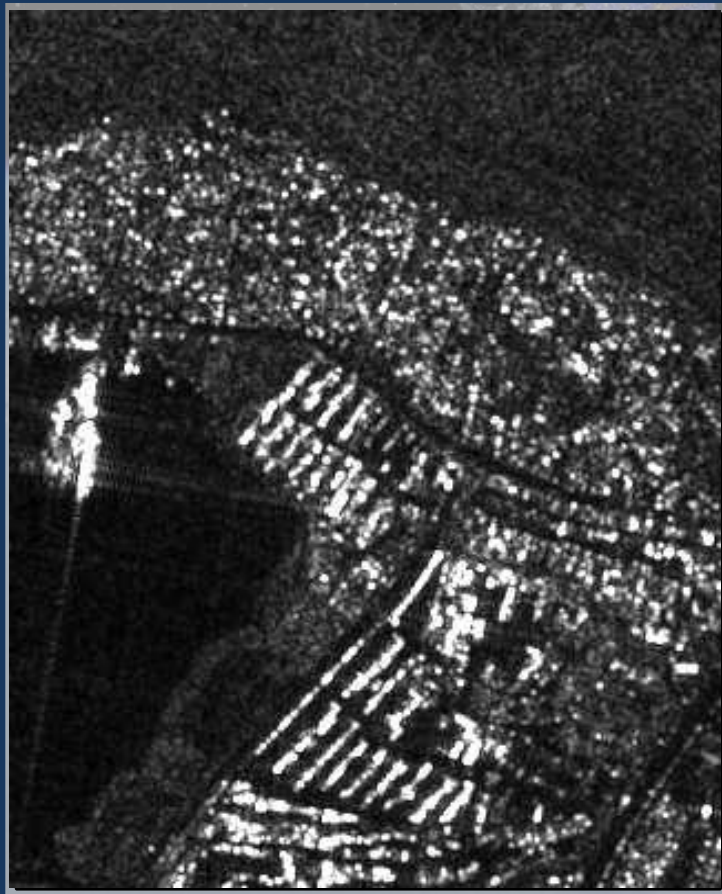
Family	Probability density function	MoLC equations
Generalized Gamma	$p_{mi}(y \theta_{mi}) = \frac{\nu_{mi}}{\sigma_{mi}\Gamma(\kappa_{mi})} \left(\frac{y}{\sigma_{mi}}\right)^{\kappa_{mi}\nu_{mi}-1} \exp\left\{-\left(\frac{y}{\sigma_{mi}}\right)^{\nu_{mi}}\right\}$	$\begin{aligned} \kappa_1 &= \Psi(\kappa)/\nu + \ln \sigma \\ \kappa_2 &= \Psi(1, \kappa)/\nu^2 \\ \kappa_3 &= \Psi(2, \kappa)/\nu^3 \end{aligned}$
Log-normal	$p_{mi}(y \theta_{mi}) = \frac{1}{\sigma_{mi}y\sqrt{2\pi}} \exp\left[-\frac{(\ln y - m_{mi})^2}{2\sigma_{mi}^2}\right]$	$\begin{aligned} \kappa_1 &= m \\ \kappa_2 &= \sigma^2 \end{aligned}$
Weibull	$p_{mi}(y \theta_{mi}) = \frac{\eta_{mi}}{\mu_{mi}^\eta} y^{\eta_{mi}-1} \exp\left[-\left(\frac{y}{\mu_{mi}}\right)^{\eta_{mi}}\right]$	$\begin{aligned} \kappa_1 &= \ln \mu + \Psi(1)\eta^{-1} \\ \kappa_2 &= \Psi(1, 1)\eta^{-2} \end{aligned}$
Nakagami	$p_{mi}(y \theta_{mi}) = \frac{2}{\Gamma(L_{mi})} (\lambda_{mi}L_{mi})^{L_{mi}} y^{2L_{mi}-1} \exp(-\lambda_{mi}L_{mi}y^2)$	$\begin{aligned} 2\kappa_1 &= \Psi(L) - \ln \lambda L \\ 4\kappa_2 &= \Psi(1, L) \end{aligned}$

Modified SEM algorithm - Settings

- Initialization: $Kmax = 6$.
- Stop criterion: Maximum number of iterations reached

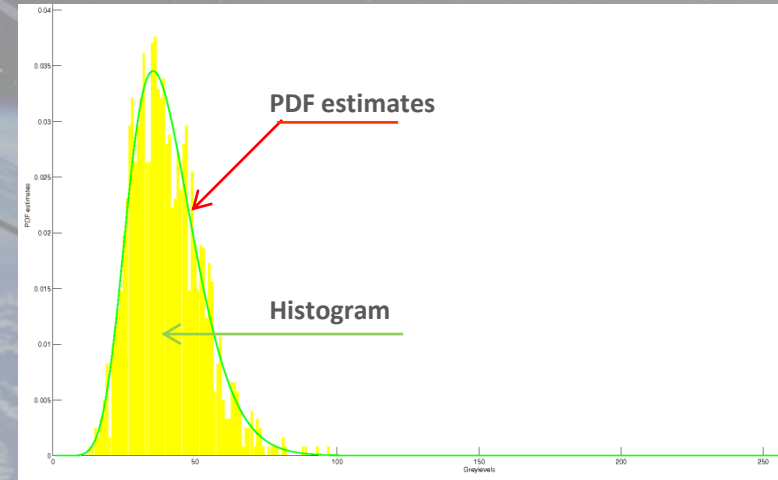
[6] Krylov, V., Moser, G., Serpico, S. B., and Zerubia, J., "Supervised high resolution dual polarization SAR image classification by finite mixtures and copulas," IEEE J-STSP, 5(3), 554-566 (2011).

Experimental validation

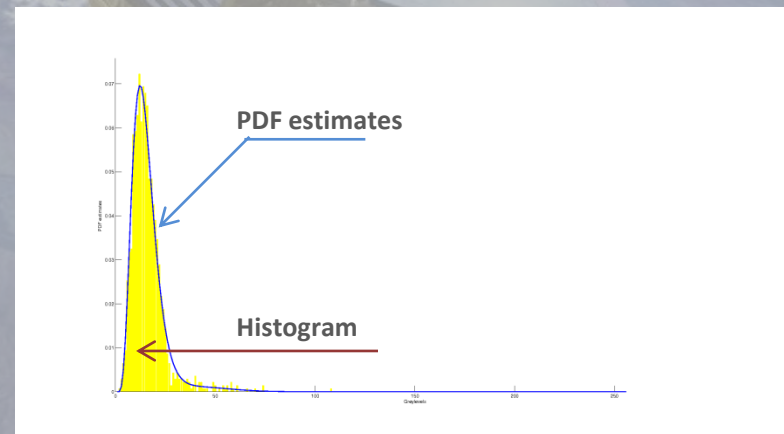


Port au Prince (CSK) © ASI

SpotLight (1m), *StripMap* (2.5m)
PingPong (10m).



Urban area modeling



Water modeling

1

Joint PDF

2

Single-scale Markovian model

❖ Markov random fields

❖ Textural features

❖ Experimental results

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Hierarchical Markovian model

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Experimental results

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Conclusion and Perspectives

General presentation

- ❖ Classification of multi-band, single-resolution acquisitions into *M classes*.
- ❖ Contextual information via MRF.
- ❖ Use the Bayesian formulation:

$$p_m(x = \omega_m | y) \propto p(x) \times p_m(y | x = \omega_m)$$

X, Y random variables and $\omega_m \in [1, M]$

Prior probabilities

For each class $m \in [1, M]$ (Gibbs):

$$p(x_s) = \frac{\exp(-U(x_s = \omega_m))}{\sum_{j=1}^M \exp(-U(x_s = \omega_j))}$$

Potts model:

$$U(x_s, \beta) = \sum_{s' \in S} \left[-\beta \sum_{s: \{s, s'\} \in C} \delta_{x_s = x_{s'}} \right]$$

where

$$\beta > 0 \quad \text{and} \quad \delta_{x_s = x_{s'}} = \begin{cases} 1, & \text{if } x_s = x_{s'} \\ 0, & \text{otherwise} \end{cases}$$

s and s' belong to the same clique C .

Optimization

- ❖ Need to maximize the posterior probability to find the labels.
- ❖ Here: **minimization of the energy function:**

$$H(x = \omega_m | y, \beta) = \sum_{t \in S} \left[-\log p_m(y_t | x_t = \omega_m) - \beta \sum_{s: \{s, t\} \in C} \delta_{x_s = x_t} \right]$$

Tools:

- ❖ **Modified Metropolis dynamics.**^[7]
- ❖ **Graph-cuts.**

[7] Berthod, M., Kato, Z., Yu, S., and Zerubia, J., "Bayesian image classification using Markov random fields," *Image and Vision Computing* 14(4), 285-295 (1996).

Textural features ^[8]

Problem: often limited class discriminability in single-pol SAR amplitudes.

Aim: Improve the classification accuracy by integrating some additional information: textural features.

- ❖ Urban area discrimination.
- ❖ Well-adapted textural feature: Haralick's Grey Level Co-occurrence Matrix (GLCM) variance.^[9]

Principle : Moving $w \times w$ window, and estimation of the value of the central pixel by using its neighborhood (calculation of spatial second-order statistics).

[8] Voisin, A., Moser, G., Krylov, V., Serpico, S. B., and Zerubia, J., "Classification of very high resolution SAR images of urban areas by dictionary-based mixture models, copulas and Markov random fields using textural features," in [Proc. of SPIE Symposium on Remote Sensing], 783000 (2010).

[9] R. M. Haralick, K. Shanmugam and I. Dinstein, "Textural features for image classification," IEEE TRans. Syst., Man, Cybern. 3(6), 610-621 (1973).

Experimental settings

- ❖ Number of classes M fixed by the user.
- ❖ MRF β parameter manually fixed (β between 1.3 and 3.7).
- ❖ Windows of size $w = 5$ for textural feature extraction.
- ❖ Ground truth sets represent 5% of the whole image.

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Joint PDF

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Single-scale Markovian model

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Hierarchical Markovian model

❖ Model presentation

❖ Transition probabilities

❖ Prior probability

4

Experimental results

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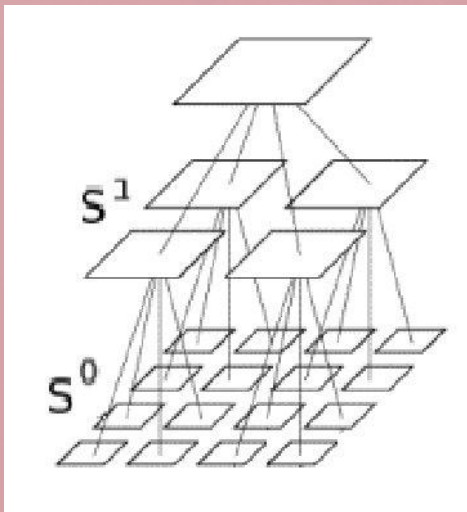
Conclusion and Perspectives

Considered DATA

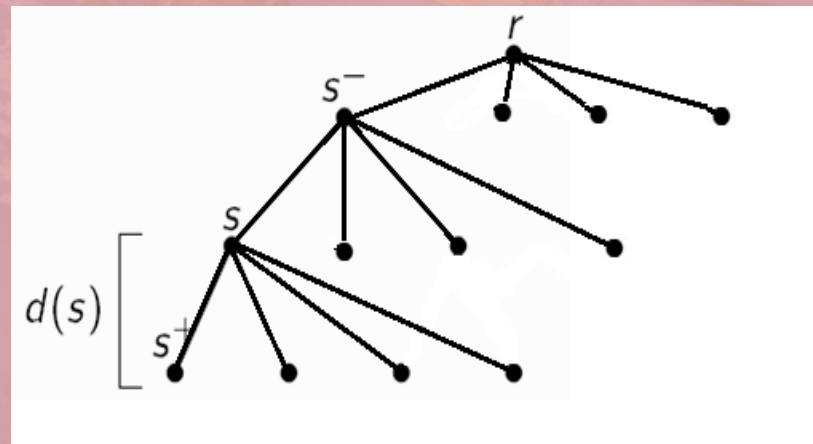
- ❖ Classification of coregistered mono-/multi-band, multi-resolution and/or multi-sensor (SAR, optical) acquisitions into M classes
- ❖ **Hierarchical graph**: use multi-resolution data.
- ❖ **Flexible** enough to take into account different kinds of statistics (multi-sensor data).

Notations

The novelty in this work is in **keeping the multi-resolution aspect** by integrating the multisensor data in an explicit **hierarchical Markovian model**, based on a **quad-tree structure**.



Hierarchical model (quad-tree)

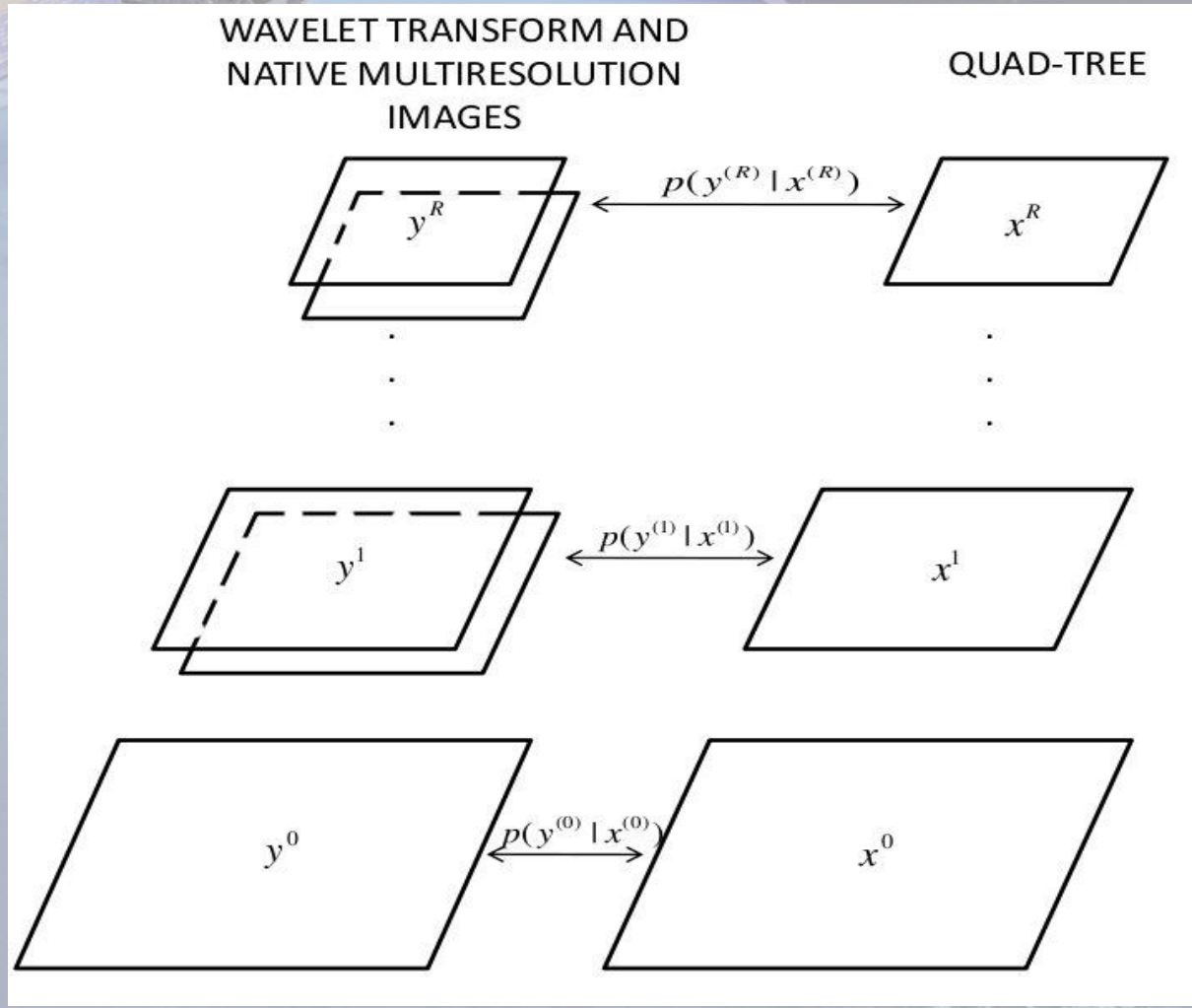


Quad-tree notations

General presentation: Hierarchical method^[10]

- ❖ **Classification**: Estimate the labels X at the finest resolution (here, level 0) given all the observations.
- ❖ **Quad-tree structure**: causality that allows to use a non-iterative algorithm.
- ❖ **MPM (marginal posterior mode)** penalizes the errors according to their number and the scale at which they occur.

Wavelet transforms are used in the proposed method to **generate multiscale features** and a **hierarchical MRF-based approach** is defined to **fuse the extracted multiscale information** and generate the output classification map.



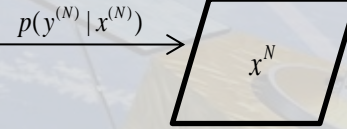
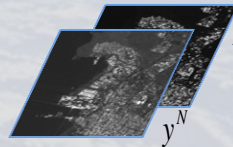
Initial marginal posterior mode (MPM) scheme

$$p_m(y^{(n)} | x_m^{(n)}) = \underbrace{p_{1m}(y_1^{(n)} | x_m^{(n)})}_{\text{finite Mixture}} \cdot \underbrace{p_{2m}(y_2^{(n)} | x_m^{(n)})}_{\text{finite Mixture}} \cdot \frac{\partial^2 C_m^* (F_{1m}(y_1^{(n)} | x_m^{(n)}), F_{2m}(y_2^{(n)} | x_m^{(n)}))}{\partial y_1^{(n)} \partial y_2^{(n)}}$$

COSMO-SkyMed Image
(Port-au-Prince Haïti,
©ASI, 2009)
and texture attribute

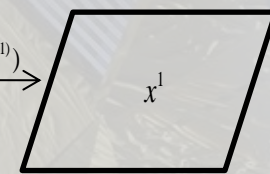
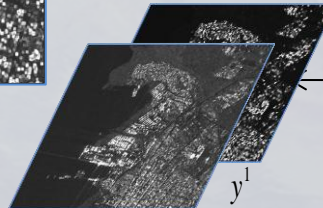


Observations



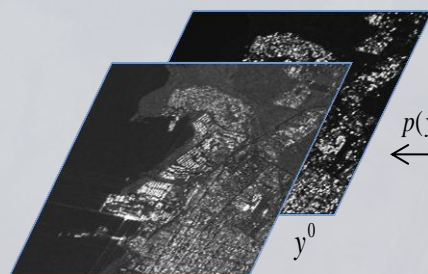
$$p(y^{(N)} | x^{(N)})$$

Observations

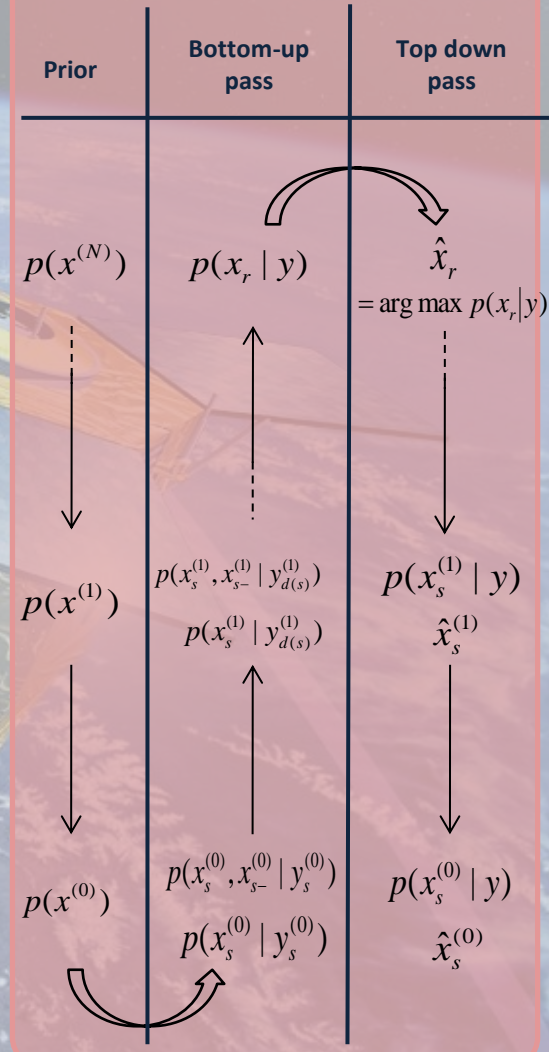


$$p(y^{(1)} | x^{(1)})$$

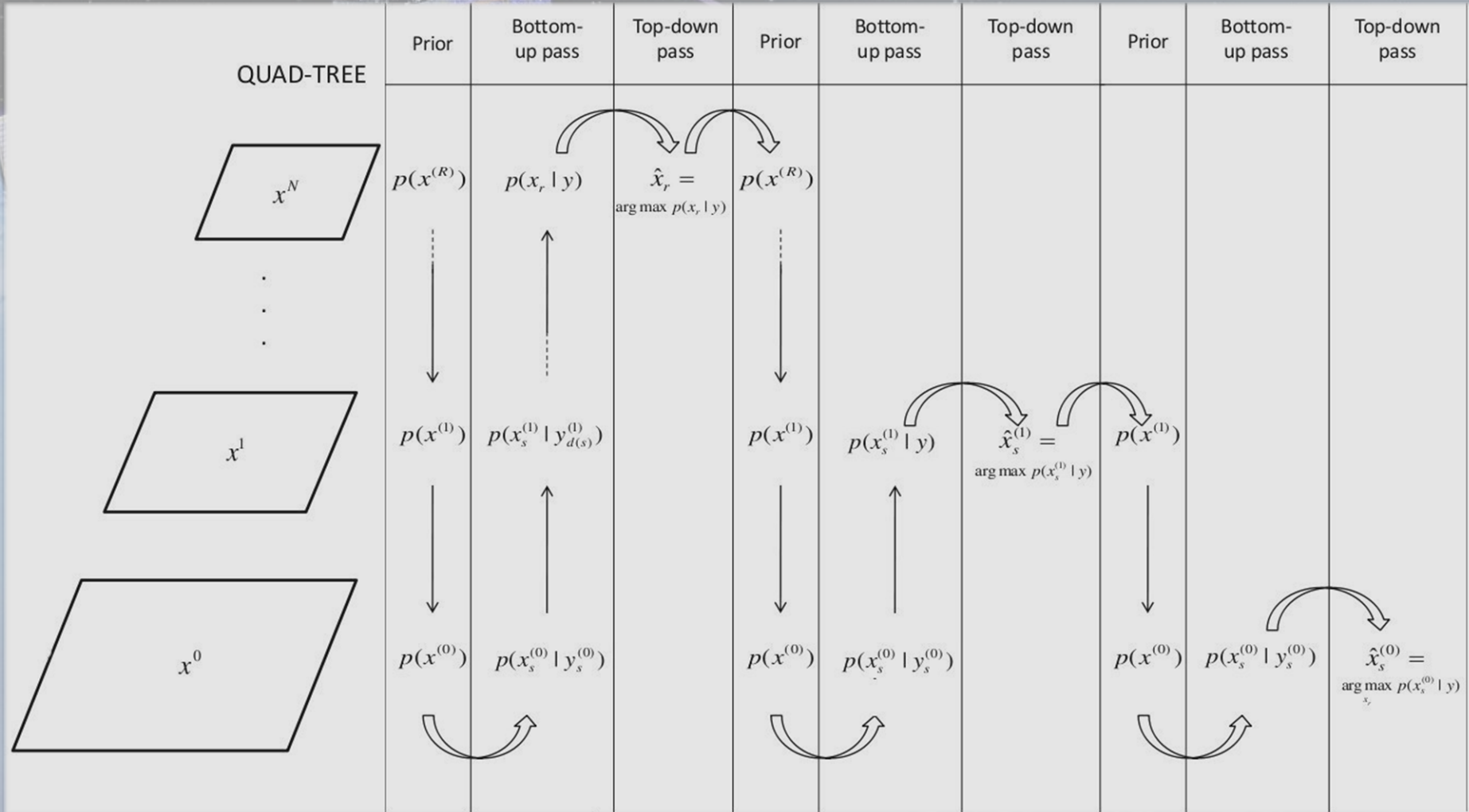
Observations



$$p(y^{(0)} | x^{(0)})$$



Global scheme - prior update [11]



[11] A. Voisin, V. Krylov, G. Moser, S.B. Serpico and J. Zerubia, "Classification of Very High Resolution SAR Images of Urban Areas Using Copulas and Texture in a Hierarchical Markov Random Field Model," IEEE Geoscience and Remote Sensing Letters, 10(1), 96-100 (2013).

Optimization

- ❖ Need to maximize the posterior probability at the coarsest scale (top-down pass).
- ❖ Tool: modified Metropolis dynamics.

Posterior probability

Expression of the partial posterior probability (bottom-up pass):

$$p(x_s | y_{d(s)}) = \frac{1}{Z} p(y_s | x_s) p(x_s) \prod_{t \in s^+} \sum_{x_t} \left[\frac{p(x_t | y_{d(t)})}{p(x_t)} p(x_t | x_s) \right]$$

Thus, we need to define the prior probabilities, the transition probabilities. The likelihood has already been defined (joint PDF at each level of the tree).

Transition probabilities ^[12]

For all sites $s \in S$ and all scales $n \in [0; R - 1]$, R corresponding to the root

$$p(x_s = \omega_m | x_{s^-} = \omega_k) = \begin{cases} \theta_n, & \text{if } \omega_m = \omega_k \\ \frac{1-\theta_n}{M-1}, & \text{otherwise} \end{cases}.$$

With
 $\theta_n > 1/M$

The transition probabilities determine the hierarchical MRF since they represent the causality of the statistical interactions between the different levels of the tree.

Prior probabilities

Prior probabilities at the coarsest level: Updated. Prior probability at level n in $[0; R - 1]$:

$$p(x_s^n) = \sum_{x_{s^-}^n} p(x_s^n | x_{s^-}^n) p(x_{s^-}^n).$$

[12] Bouman, C. and Shapiro, M., "A multiscale random field model for Bayesian image segmentation," IEEE Trans. Image Process. 3(2), 162-177 (1994).

General presentation: Example of multisensor data classification

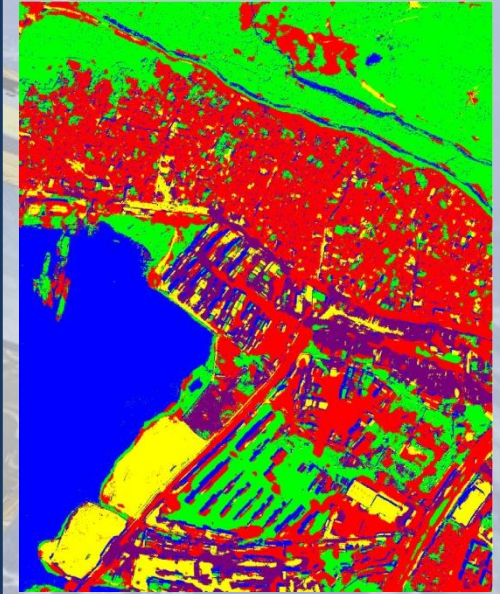
Example of classification result for a multi-sensor acquisition over the Port au-Prince quay (Haiti).



SAR image (©ASI, 2010)
(2.5 m)



Optical image
(©GeoEye, 2010) (0.625 m)



Hierarchical MRFbased
classification
(optical+ SAR)

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Joint PDF

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Single-scale Markovian model

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Hierarchical Markovian model

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Experimental results

- ❖ **Experimental settings**
- ❖ **Port-au-Prince acquisition**

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Conclusion and Perspectives

Experimental settings

- ❖ Number of classes M fixed by the user.
- ❖ $\Theta_n = 0.85$ (transition probability).
- ❖ For native single-resolution images, the multi-resolution acquisitions are obtained by wavelet transform (Daubechies^[12] and Haar) on $R = 3$ levels.

Multi-sensor acquisition of Port-au-Prince (Haiti)

2 coregistered images of the quay of Port-au-Prince (Haiti):

- ❖ A single-polarized COSMO-SkyMed SAR image (©ASI,2010), HH polarization, StripMap acquisition mode (2.5 m pixel spacing), geocoded, single-look of 320×400 pixels.
- ❖ A pan-sharpened (1-band) GeoEye acquisition (©GeoEye, 2010, 0.625 m pixel spacing) of 1280×1600 pixels.

General presentation: Example of multisensor data classification

Classification results, 5 classes: **water**, **urban**, **vegetation**, **sand**, and **containers**.

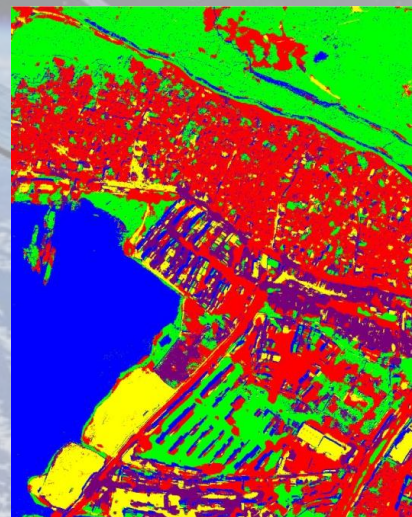


Optical image

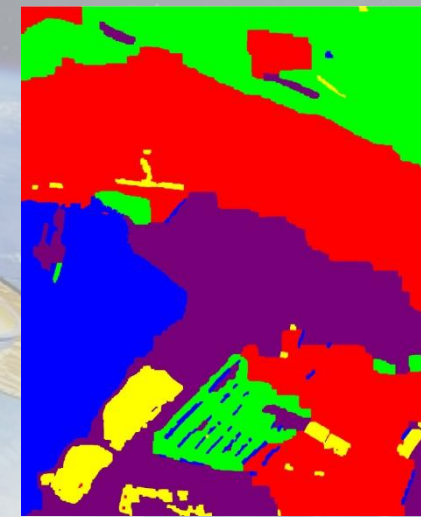
(©GeoEye, 2010) 0.625 m



K-means



**Hierarchical
MRF-based classifier**



Single-scale MRF

Port-au-Prince, Haiti

	water	urban	vegetation	sand	containers	overall	Time Exec
Proposed SAR+optical	100%	75.24%	87.16%	98.89%	49.31%	82.12%	≈30 min
Single-scale MRF	100%	100%	81.42%	99.94%	59.62%	88.20%	≈6 min
K-means	100%	39.01%	91.19%	82.32%	6.54%	57.30%	

Experiments were conducted on an Intel Xeon quad-core(2.40 GHz and 12-MB cache) 18-GB-RAM 64-bit Linux system. SAR image (320x400) and optical image (1280x1600).

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Joint PDF

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Single-scale Markovian model

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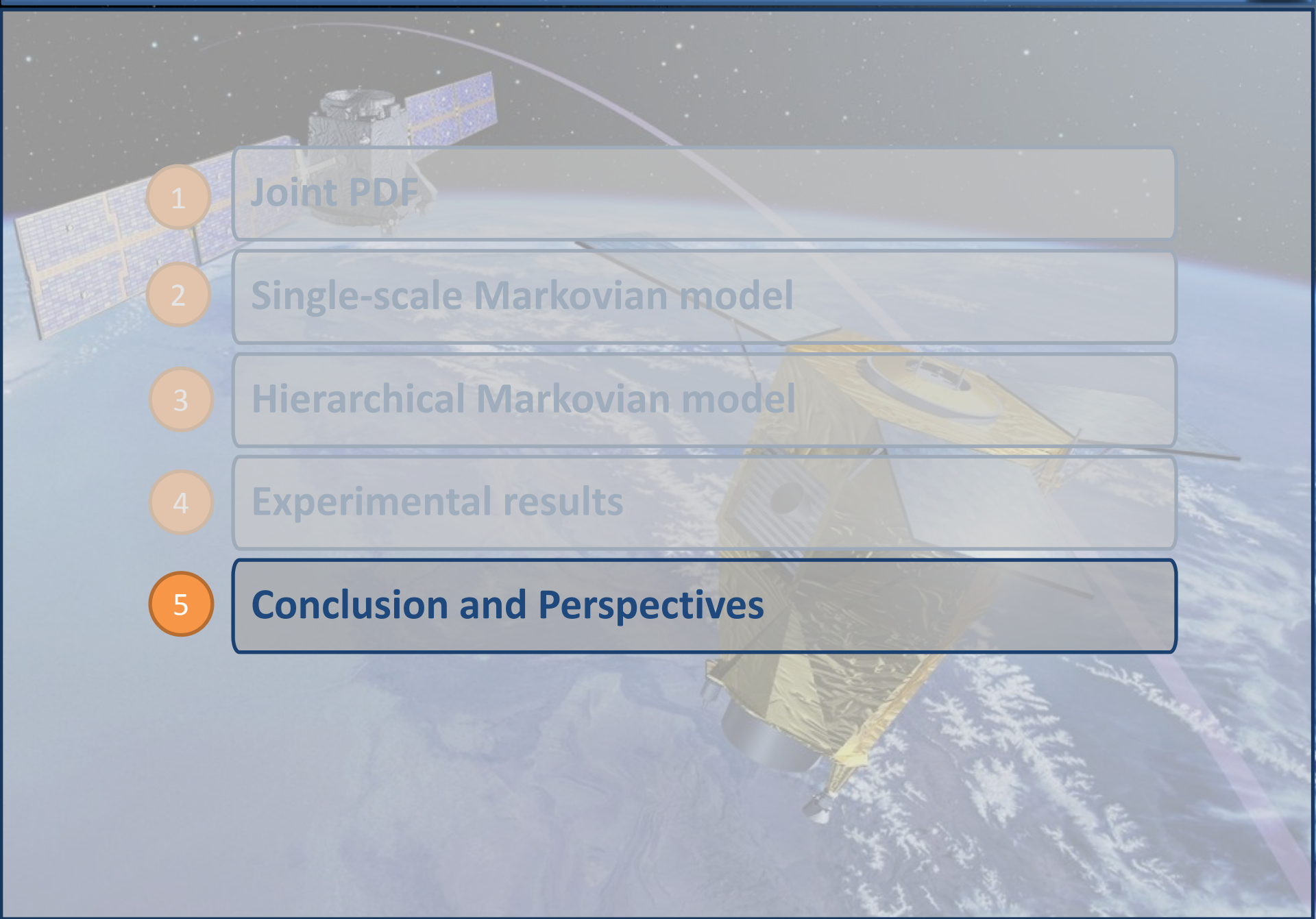
Hierarchical Markovian model

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Experimental results

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Conclusion and Perspectives



Conclusion

- ❖ Urgent need of more data with ground truth on Haïti (Both CSK and Pleiades) to validate the proposed methods.
- ❖ Satisfying classification results obtained by using these Markovian methods. (Smoothing effect of the MRF.)
- ❖ Details provided by the hierarchical MRF.
- ❖ Selection of the best method according to the user.

Perspectives

- ❖ Extension of the previous methods to :
 - ❖ Change detection
 - ❖ Satellite image time series analysis
- ❖ Extension of the copula dictionary

Acknowledgments

We would like to thank :

- ❖ The Direction Générale de l'Armement (**DGA**, France) and Institut National de Recherche en Informatique et Automatique (**INRIA**, France) for the partial financial support.
- ❖ The Italian Space Agency (**ASI**, Italy) for providing the COSMO-SkyMed images
- ❖ **GeoEye Inc.** And **Google crisis** response for providing the GeoEye images.
- ❖ The Centre National d'Etudes Spatiales (**CNES**, France) for providing Pleiades data in the near future.

A satellite with a black body and two large, rectangular solar panel arrays extending outwards. The panels are covered in a grid of small, blue solar cells.

COSMO-SkyMed (CSK) © ASI

A satellite with a gold-colored body and two large, rectangular solar panel arrays extending outwards. The panels are covered in a grid of small, blue solar cells. A purple beam of light is shown emanating from the satellite.

Pléiades © CNES

**Thank you For your
attention**

For more information : <https://team.inria.fr/ayin/>
And previously <https://www-sop.inria.fr/ariana/>